

Auralisation de trafics routiers non-stationnaires en milieu urbain basée sur une synthèse granulaire temps réel

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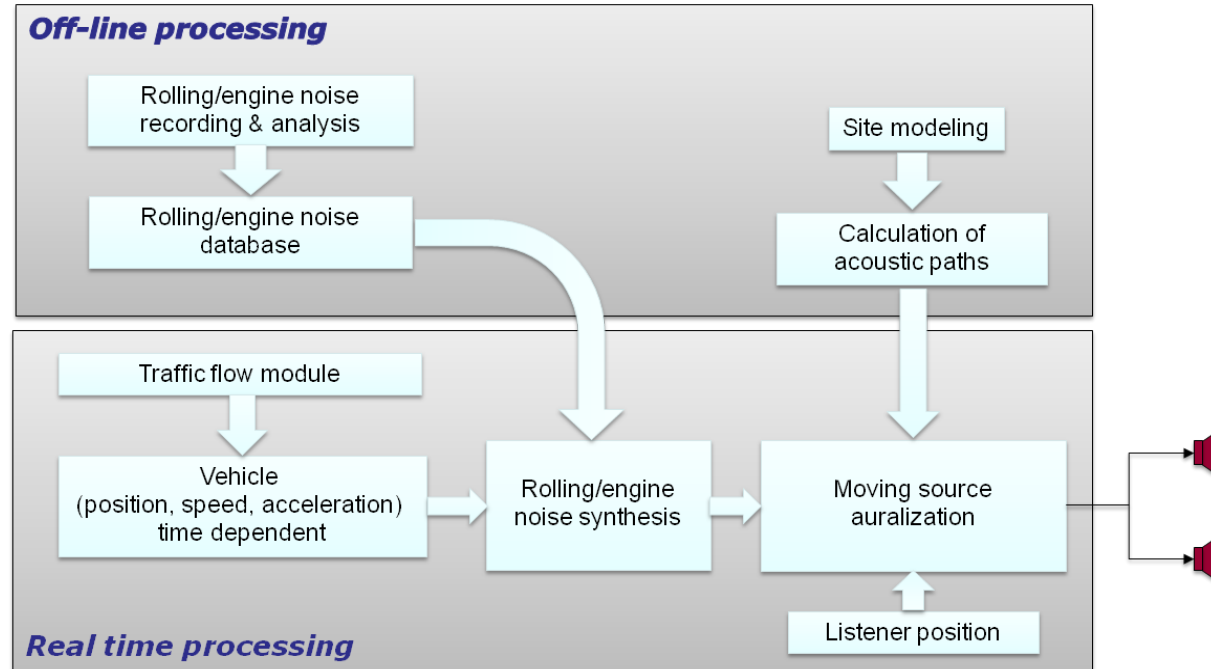
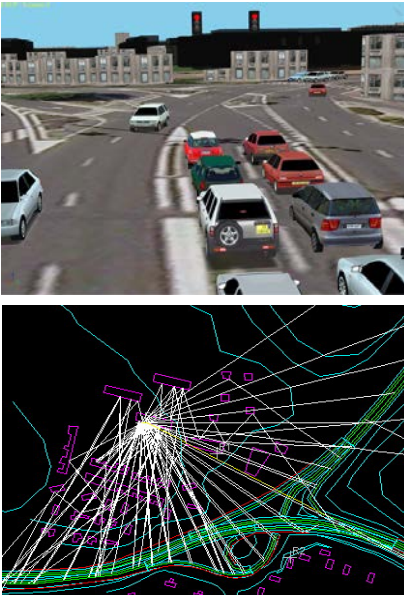
- ✓ Context
- ✓ Auralization framework
 - ✓ Overview
 - ✓ Source signal synthesis
- ✓ Quantitative validation
 - ✓ Approach
 - ✓ Results
- ✓ Audio samples
- ✓ Conclusions

Context

Perceptive evaluation of noise pollution

- ✓ Analyse (engineers) or facilitate awareness (decision makers) of noise pollution
- ✓ Extend standard tools based on sound pressure levels only
- ✓ Make acoustic simulation results 'audible'
- ✓ Requirements
 - ✓ Render a close version of the real sound field
 - ✓ Provide user interaction for comparative listening tests
- ✓ Challenge
 - ✓ Satisfy both physical accuracy and user interaction with limited computational resources

- ✓ Novel approach for the auralization of non-stationary road traffic noise
- ✓ 3 main tasks :
 - ✓ synthesis of source signals (engine and rolling noise for varying speed)
 - ✓ modeling of sound propagation
 - ✓ spatial audio rendering



- ✓ Engine noise recording at varying rpm (vehicle at rest)
- ✓ Rolling noise recording at varying speed (CPX method)



GRANULAR SYNTHESIS FRAMEWORK

OFF-LINE ANALYSIS

Source signal recording



Estimation of control parameter evolution



Extraction marks location



Sound sample extraction

REAL TIME SYNTHESIS

Control parameter target values



Sound sample selection



Overlap-and-add processing

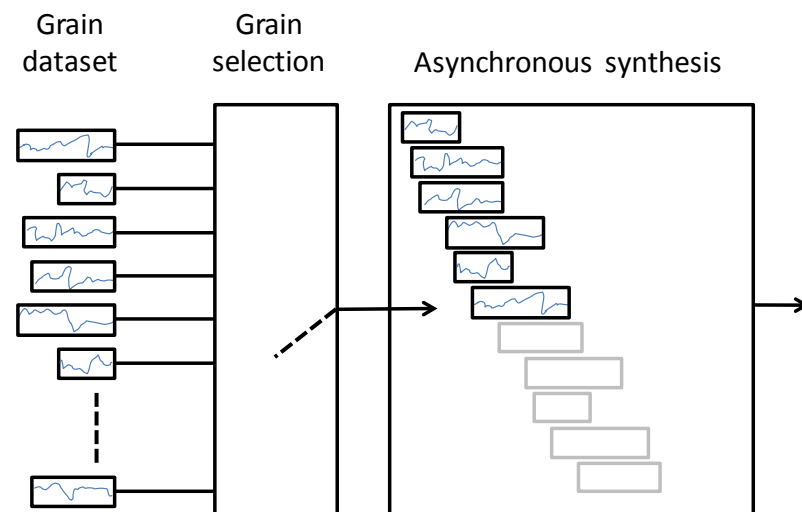
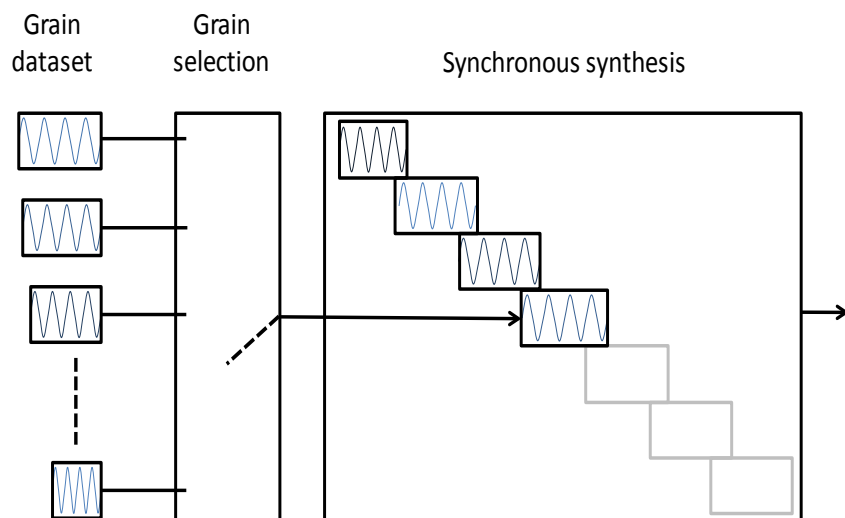
Auralization framework

Source signal synthesis (cont'd)

Sample Overlap-And-Add for real time synthesis

Engine noise: Synchronous synthesis
(1 sample = 1 full engine cycle)

Rolling noise: Asynchronous synthesis



- ✓ Source signals represent equivalent source in free field at 1 m
- ✓ Constant calibration gain applied to extracted sound samples
- ✓ Based on the Harmonoise vehicle emission model according to

Rolling noise calibration gain

$$G_{R,cal} = 10 \log_{10} \left(\sum_{i=1}^M \left(10^{(E_R(v_i) - L_{WR,A}(v_i))/10} \right) P(v_i) \right)$$

Engine noise calibration gain

$$G_{P,cal} = 10 \log_{10} \left(\sum_{i=1}^M \left(10^{(E_P(v_i) - L_{WP,A}(v_i))/10} \right) P(v_i) \right)$$

Where $L_{WR,A}(v_i)$ reference rolling noise power in dB(A) at speed v_i
 $L_{WP,A}(v_i)$ reference engine noise power in dB(A) at speed v_i
 $P(v_i)$ propability of occurrence of speed v_i
 $E_R(v_i)$ energy in dB(A) of synthesized rolling noise signal at speed v_i

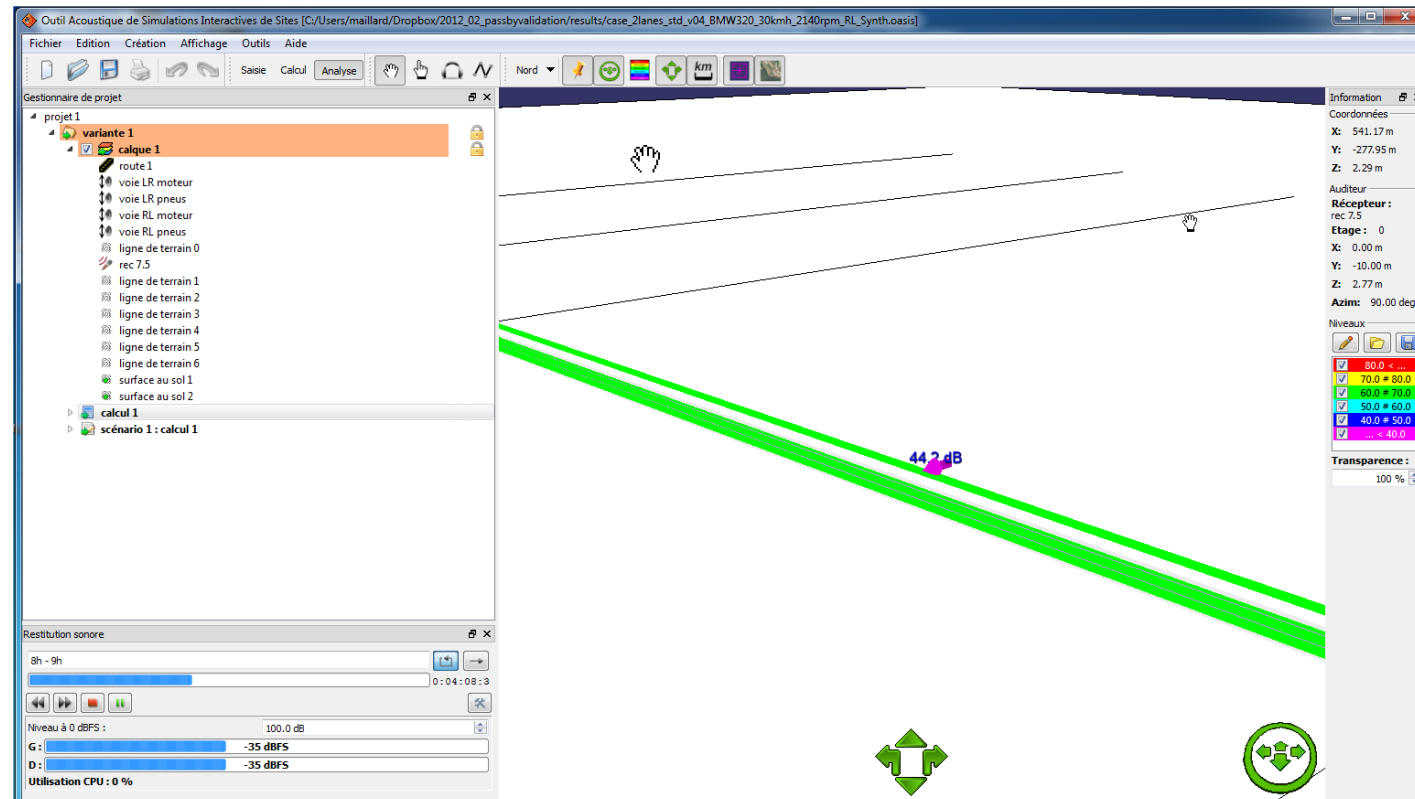
$$E_P(v_i) = 10 \log_{10} \left(\sum_{g=2}^5 \left(10^{E_P(v_i,g)/10} \right) P(g, v_i) \right) \text{ averaged energy in dB(A) of synthesized engine noise at speed } v_i$$

$E_P(v_i, g)$ energy in dB(A) of synthesized engine noise signal at speed v_i and gear g
 $P(g, v_i)$ probability of driving at gear g for speed v_i

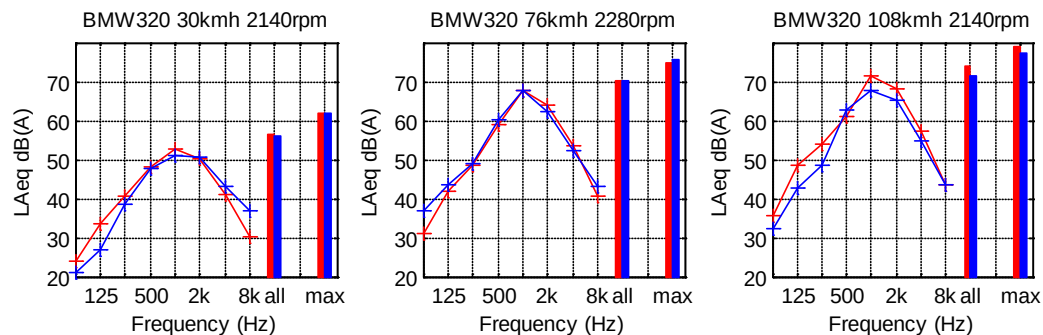
- ✓ Compare sound pressure levels of auralized and recorded sequences
- ✓ Single vehicles passing by the listening point at different speeds
- ✓ Straight road in open field
- ✓ 5 vehicles / 3 speeds
- ✓ Measure SPL + speed
- ✓ Binaural / Stereo recordings



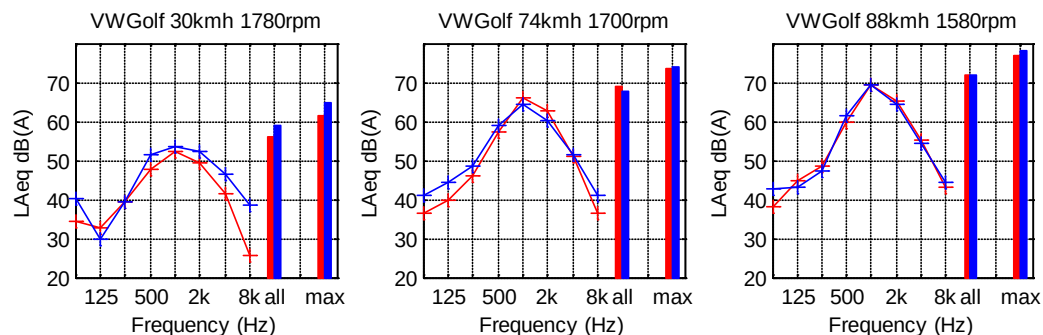
- ✓ Engine and rolling noise dataset from CPX recording on same road / vehicles
- ✓ Site modeling
(approximate terrain data and ground properties)
- ✓ Auralization
- ✓ Signal analysis
(Leq, Lamax, ...)
- ✓ Listening tests



BMW 320

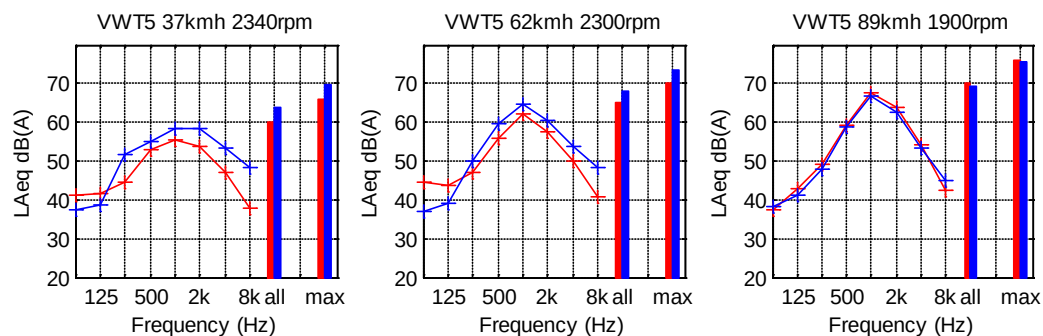


Volkswagen Golf

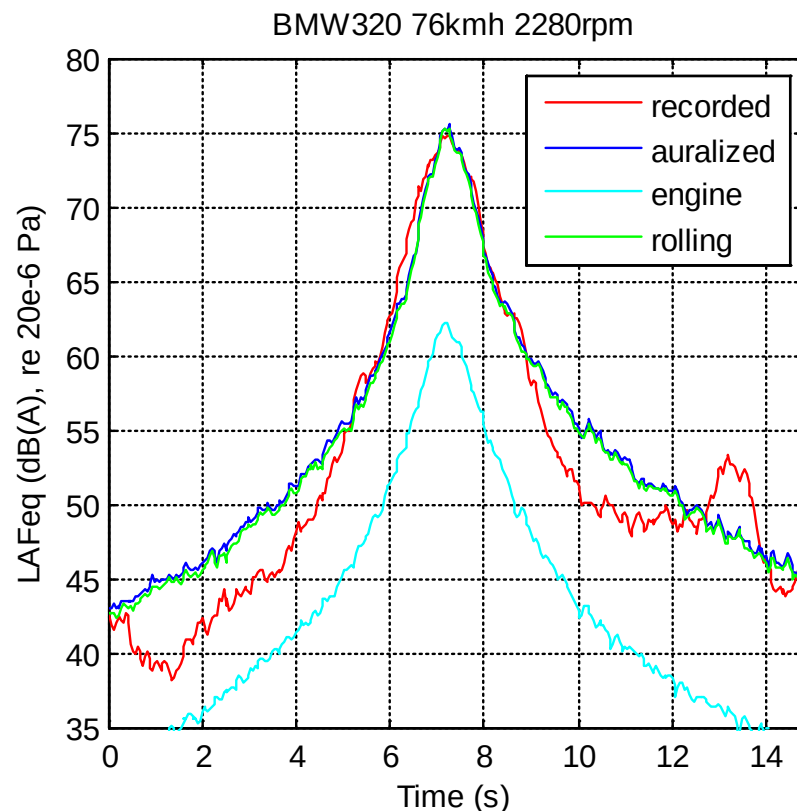
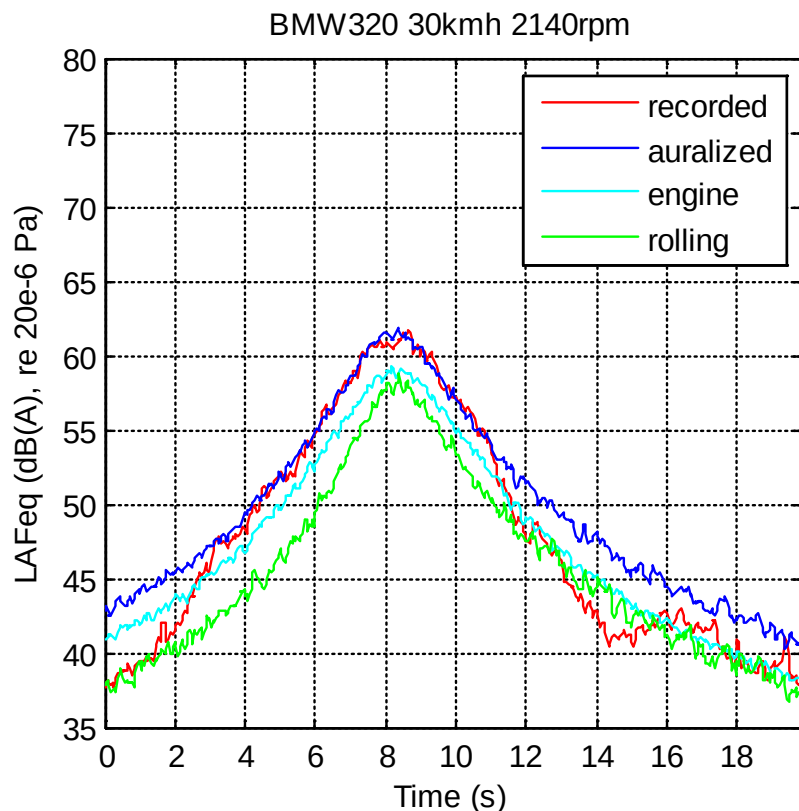


----- recorded
----- auralized

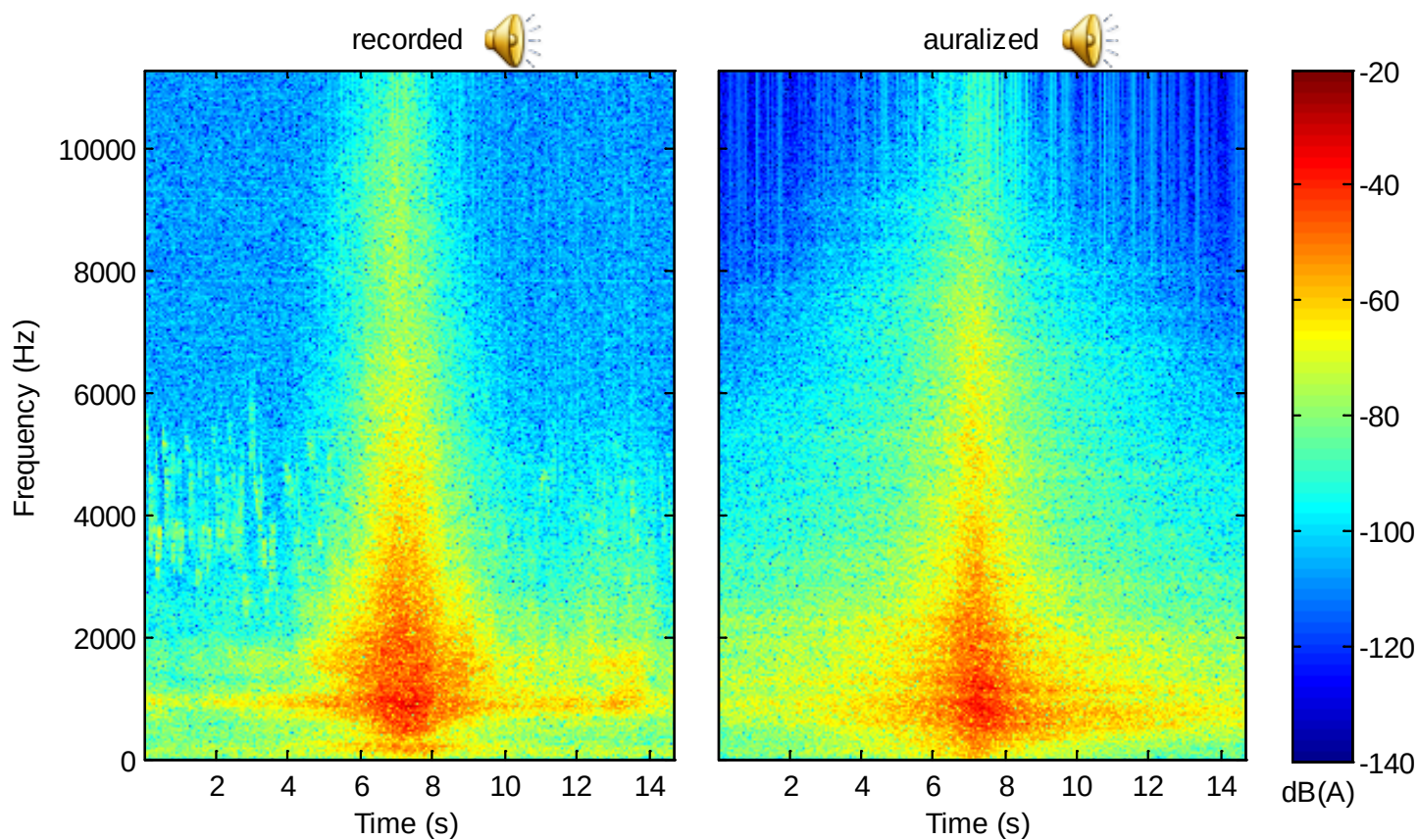
Volkswagen Transporter



BMW 320 – LAFeq vs Time

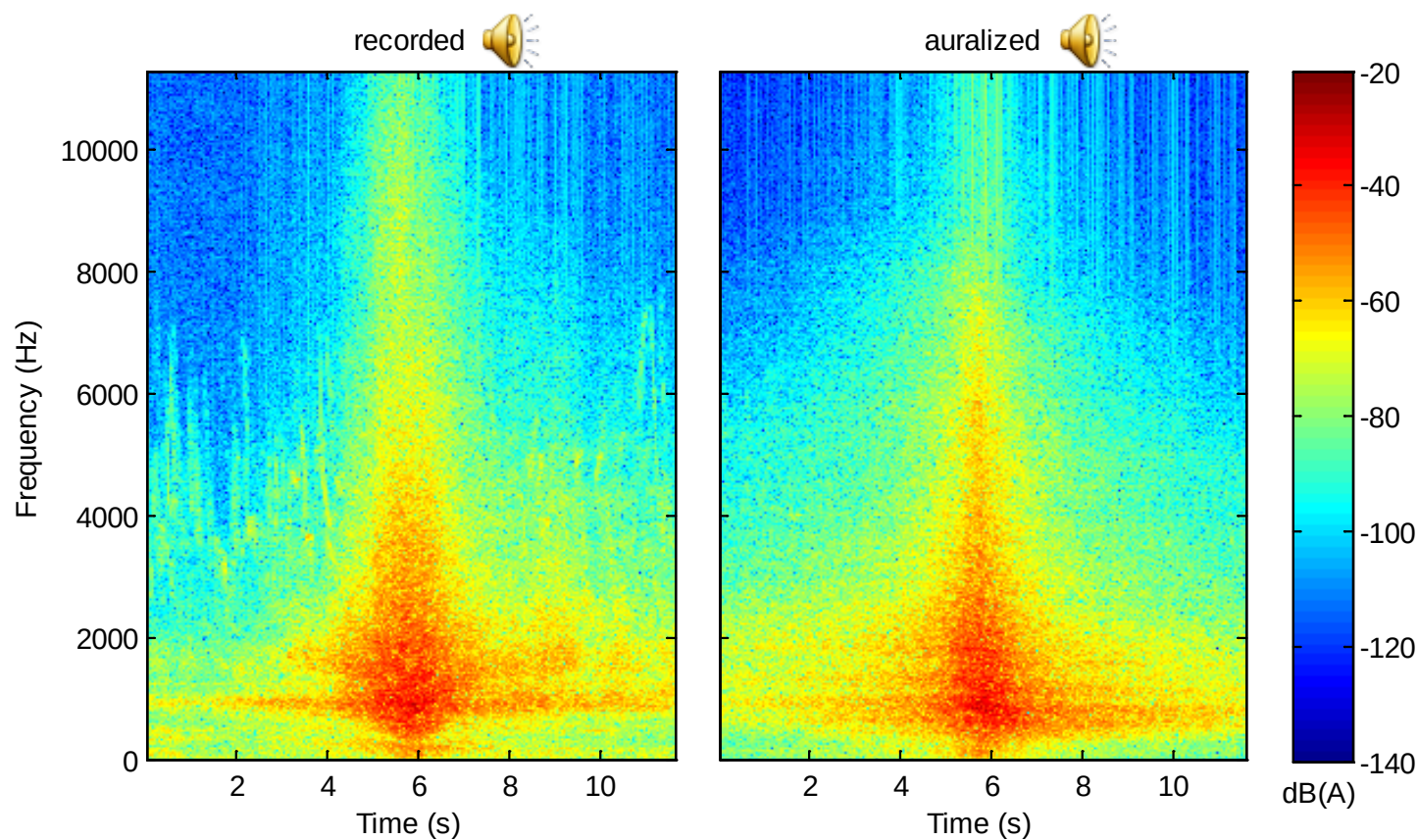


BMW 320 - 76 km/h - 2280 rpm



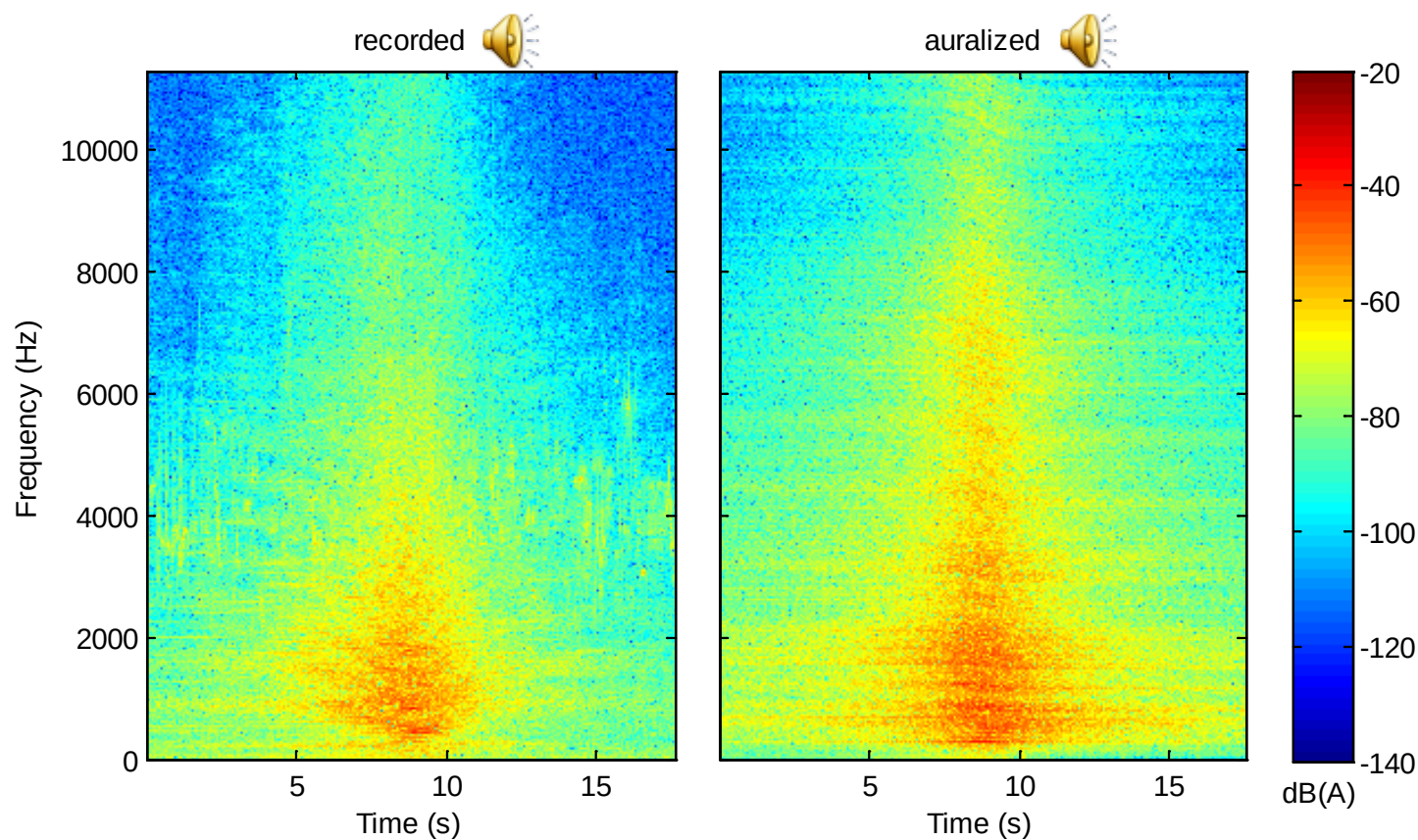
Quantitative validation Audio samples (cont'd)

Golf - 88 km/h - 1580 rpm



Quantitative validation Audio samples (cont'd)

Transporter - 37 km/h - 2340 rpm



Audio samples

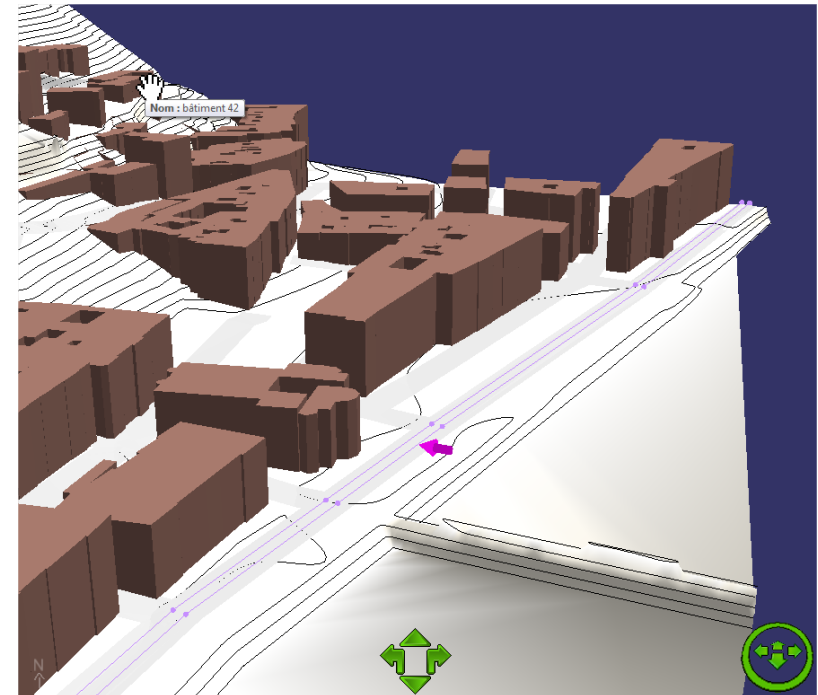
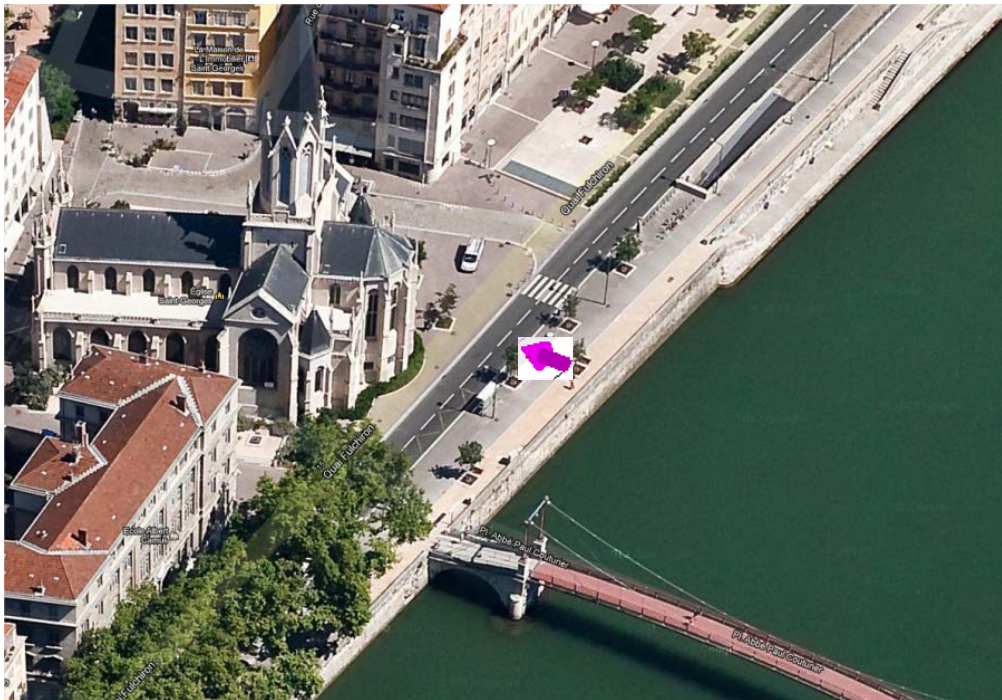
Real traffic in urban site

- ✓ Two lane road
- ✓ Two stop lights
- ✓ 800 vehicles per hour
- ✓ averaged speed = 47 km/h

Auralized trafic



Auralized vs recorded



- ✓ New approach for the auralization of road traffic noise
 - ✓ Real time auralization
 - ✓ Non-stationary traffic flows with varying vehicle speed

- ✓ First quantitative results for
 - ✓ Single vehicles / constant speed / receiver close to road
 - ✓ Good agreement between SPL of recorded and auralized sequences

- ✓ Current work:
 - ✓ Perceptual analysis of auralized sequences
 - ✓ Quantitative and perceptual validation extended to
 - ✓ non-stationary traffic conditions
 - ✓ more complex urban site

- ✓ This research has been undertaken in the frame of the European project number 234306 HOSANNA
- ✓ Müller-BBM participated in the measurement campaign and provided the pass-by SPL data and tire noise CPX recordings